
Distributed On-the-Fly Model Checking and Test Case Generation

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Context and motivation

- Explicit-state verification of concurrent systems
- Combine two approaches to fight state explosion
 - *On-the-fly* verification
 - Incremental state space construction
 - *Distributed* verification
 - State space exploration using several machines connected by a network

Two problems

- Model checking of alt-free μ -calculus
- Conformance test case generation

One solution

- Translation to a boolean equation system resolution
- Use of diagnostic generation

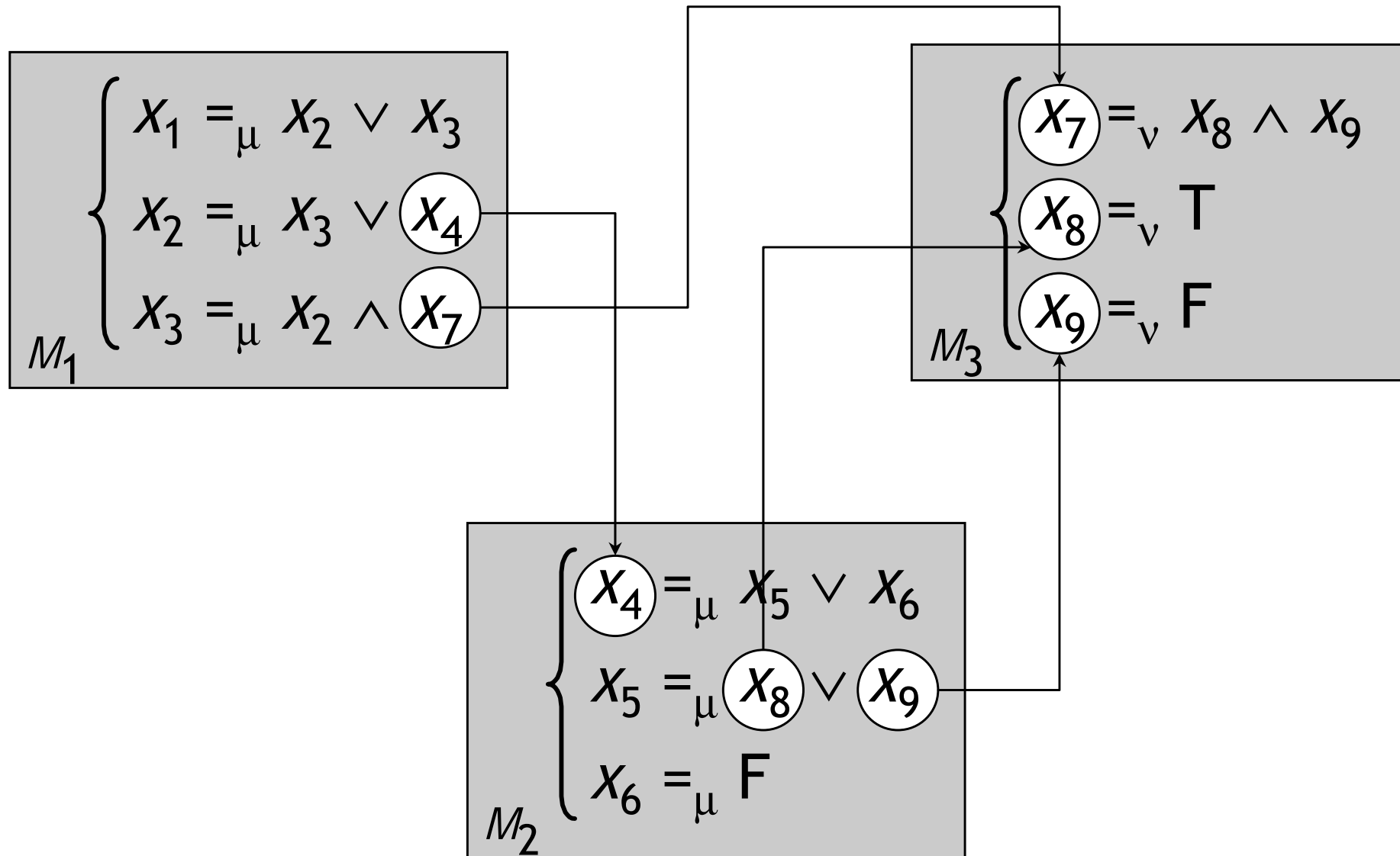


Outline

- Boolean equation systems
- Distributed local resolution algorithm
- Model checking of alternation-free mu-calculus
- Conformance test case generation
- Performance measures
- Conclusion and future work



Boolean equation systems (alternation-free)



Sequential local resolution

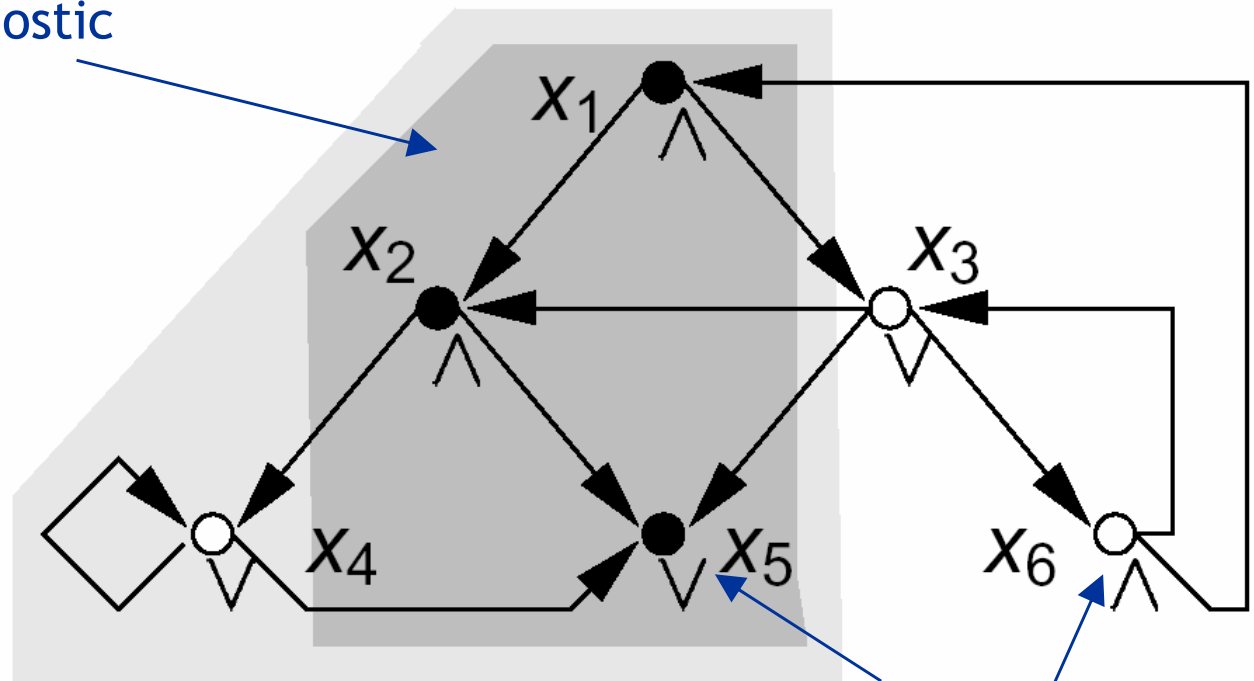
BES

$$\left\{ \begin{array}{l} X_1 =_{\vee} X_2 \wedge X_3 \\ X_2 =_{\vee} X_4 \wedge X_5 \\ X_3 =_{\vee} X_2 \vee X_5 \vee X_6 \\ X_4 =_{\vee} X_4 \vee X_5 \\ X_5 =_{\vee} \text{false} \\ X_6 =_{\vee} X_1 \wedge X_3 \end{array} \right.$$

boolean graph

[Andersen-94]

diagnostic



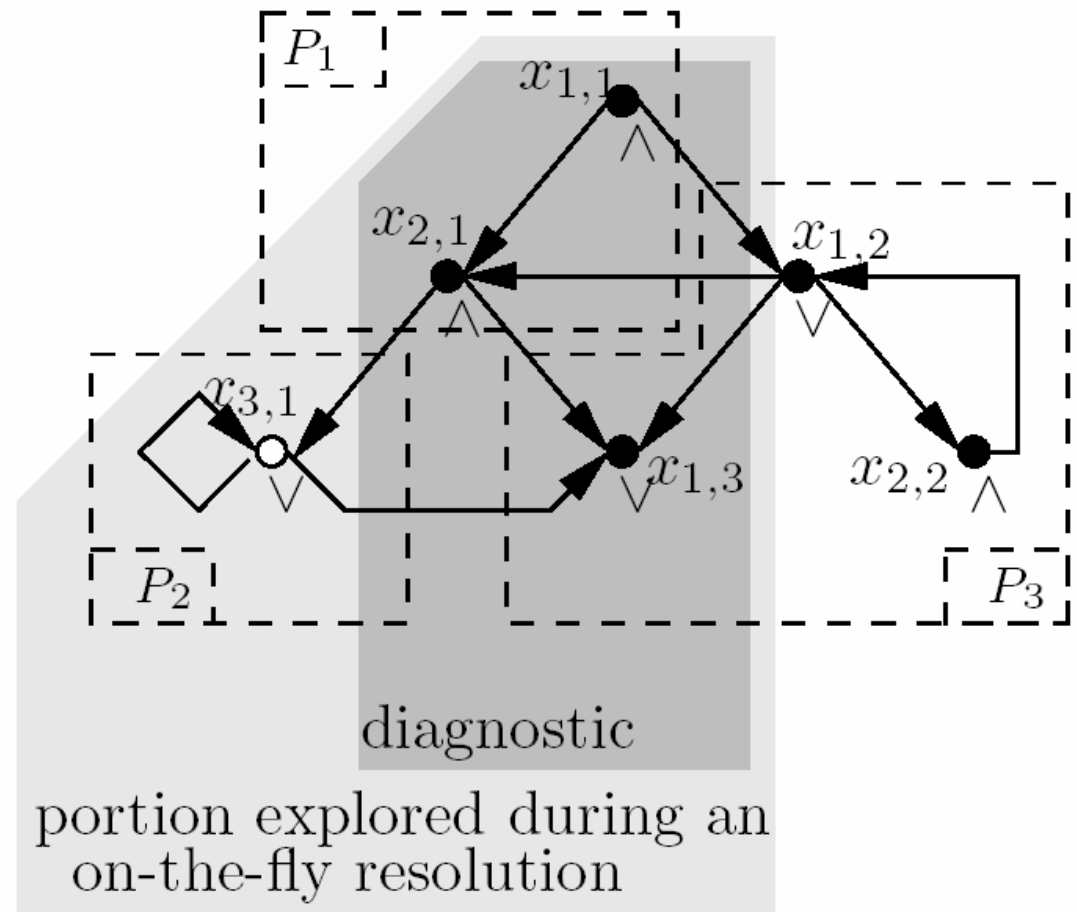
- **Caesar_Solve** library [Mateescu-03,06]

- 5 resolution algorithms + diagnostic generation



Distributed local resolution

$$\begin{array}{l}
 \text{block 1} \left\{ \begin{array}{l} x_{1,1} \stackrel{\nu}{=} x_{2,1} \wedge x_{1,2} \\ x_{2,1} \stackrel{\nu}{=} x_{3,1} \wedge x_{1,3} \\ x_{3,1} \stackrel{\nu}{=} x_{3,1} \vee x_{1,3} \end{array} \right. \\
 \\
 \text{block 2} \left\{ \begin{array}{l} x_{1,2} \stackrel{\mu}{=} x_{2,1} \vee x_{1,3} \vee x_{2,2} \\ x_{2,2} \stackrel{\mu}{=} x_{1,2} \end{array} \right. \\
 \\
 \text{block 3} \left\{ \begin{array}{l} x_{1,3} \stackrel{\nu}{=} \text{false} \end{array} \right.
 \end{array}$$



- MB-DSolve algorithm

- Two distributed BFS traversals of the boolean graph (forward expansion and backward stabilization)
- Partial distributed termination detection (stabilization of a portion of a block)

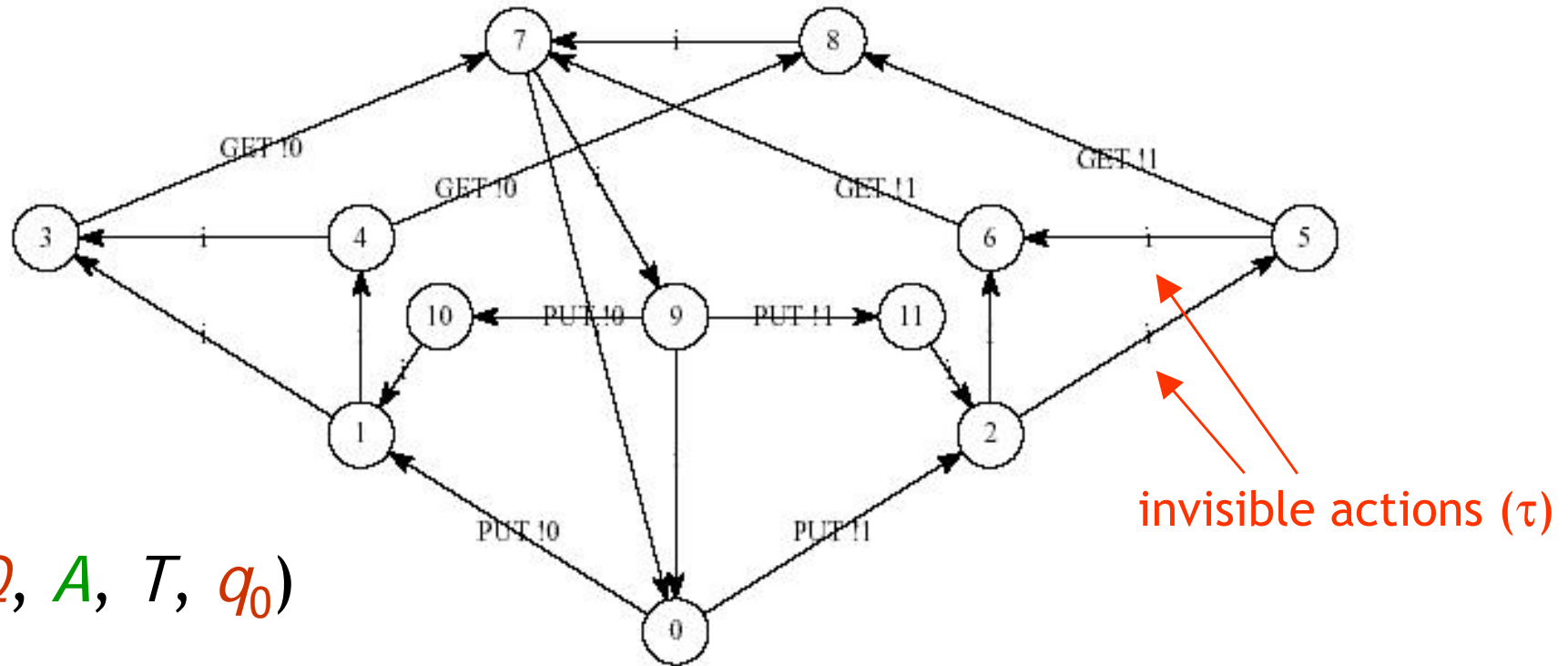
Related work

(distributed model checking)

- Linear temporal logic
 - Safety properties [Lerda-Sisto-99]
 - Distributed non-nested DFS
 - Full LTL [Barnat-Brim-Stribrna-01]
 - Distributed nested DFS
- Modal μ -calculus
 - Alternation depth 1 [Bollig-Leucker-Weber-02]
 - Alternation depth 2 [Leucker-Somla-Weber-03]
[Holmen-Leucker-Lindstrom-04]
 - Distributed game graph exploration
 - UppDMC tool



Labelled Transition Systems

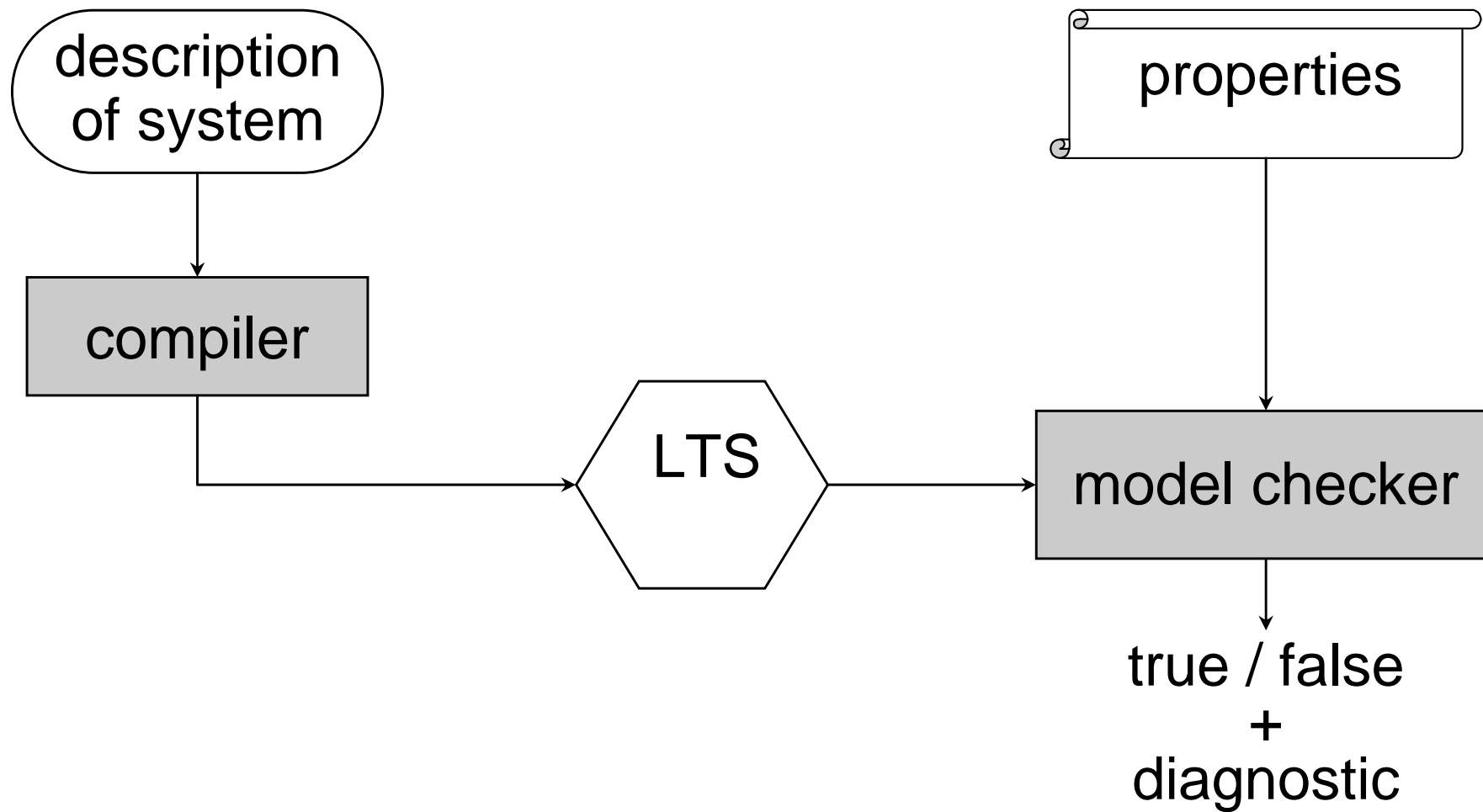


CADP toolbox (<http://www.inrialpes.fr/vasy/cadp>)

- **Explicit representation**
(succ/pred function)
 - **BCG** (Binary Coded Graphs)
- **Implicit representation**
(successor function)
 - **OPEN/CAESAR** [Garavel-98]



Model checking



Modal mu-calculus

Let $M = (Q, A, T, q_0)$ be an LTS.

Action formulas

$$\alpha ::= a \mid \neg\alpha \mid \alpha_1 \vee \alpha_2 \mid \alpha_1 \wedge \alpha_2$$

State formulas

$$\begin{aligned} \varphi ::= & F \mid T \mid \neg\varphi \mid \varphi_1 \vee \varphi_2 \mid \varphi_1 \wedge \varphi_2 \\ & \mid \langle \alpha \rangle \varphi \mid [\alpha] \varphi \\ & \mid X \mid \mu X . \varphi \mid \nu X . \varphi \end{aligned}$$



Alternation-free fragment

- No mutual recursion between minimal and maximal fixed point variables [Emerson-Lei-86]

- Example:

“every SEND is eventually followed by a RECV”

$\nu X . [\text{SEND}] (\mu Y . \langle T \rangle T \wedge [\neg \text{RECV}] Y) \wedge [T] X$

- Equational form HMLR [Larsen-88]:

$\{ X =_{\nu} [\text{SEND}] Y \wedge [T] X \}$

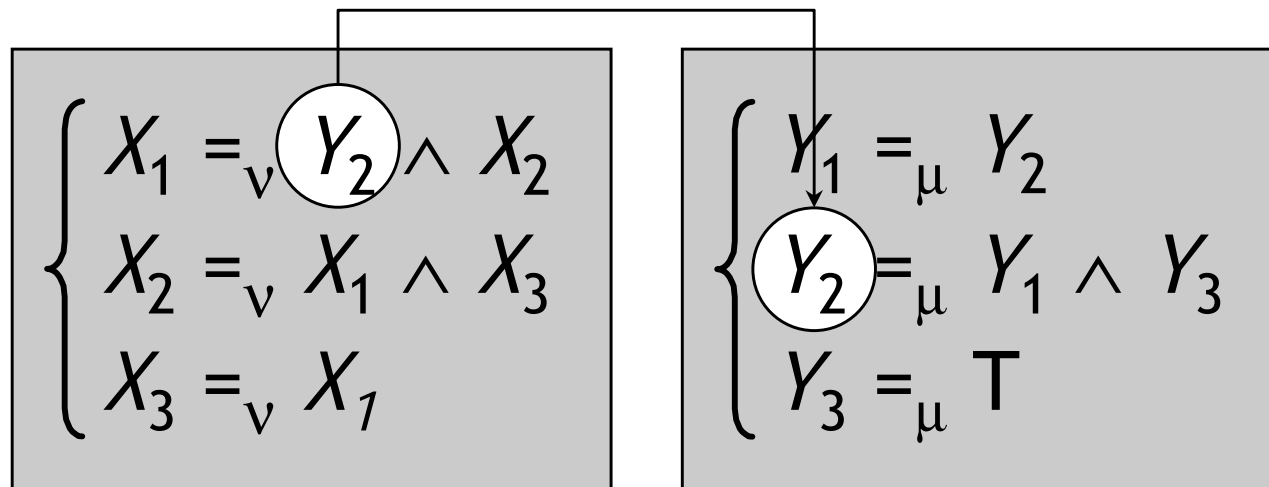
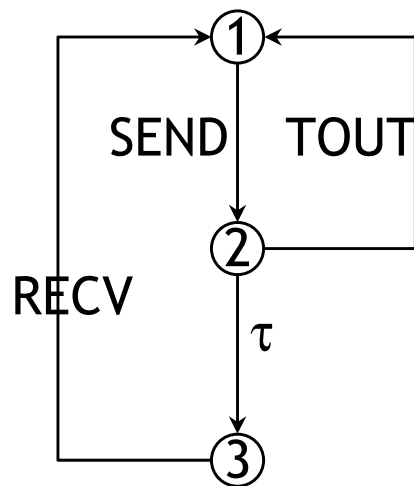
$\{ Y =_{\mu} \langle T \rangle T \wedge [\neg \text{RECV}] Y \}$

(no cyclic dependencies between blocks)

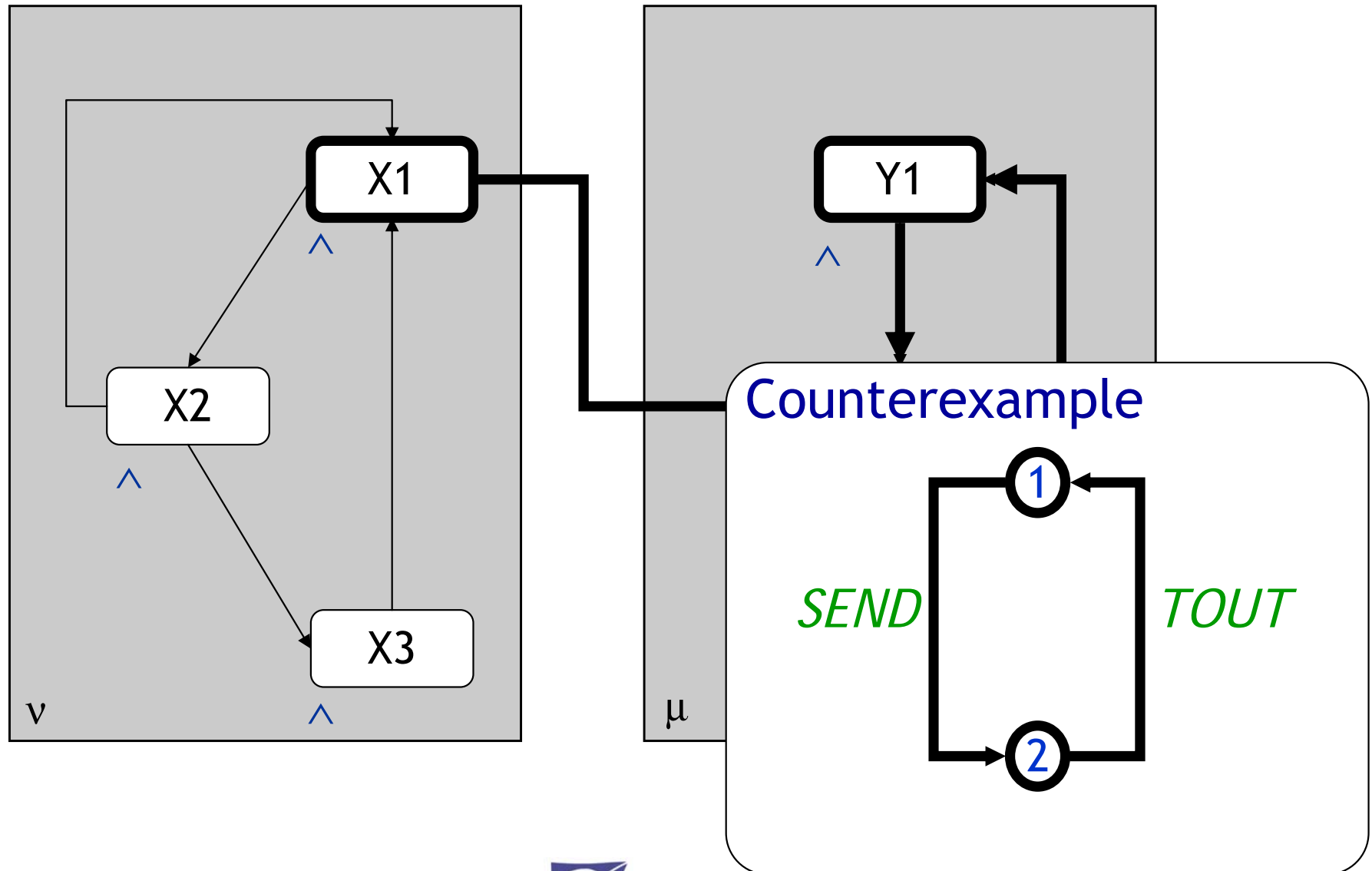


Translation to BESs

- Principle: $s \models X$ iff X_s is true
- Formula: $\{ X =_v [\text{SEND}] Y \wedge [\text{T}] X \}$
 $\{ Y =_\mu \langle \text{T} \rangle \text{T} \wedge [\neg \text{RECV}] Y \}$
- BES: $\{ X_s =_v (\wedge_{s' \rightarrow \text{SEND } s'} Y_{s'}) \wedge (\wedge_{s' \rightarrow s'} X_{s'}) \}$
 $\{ Y_s =_\mu (\vee_{s' \rightarrow s'} \text{T}) \wedge (\wedge_{s' \rightarrow \neg \text{RECV } s'} Y_{s'}) \}$

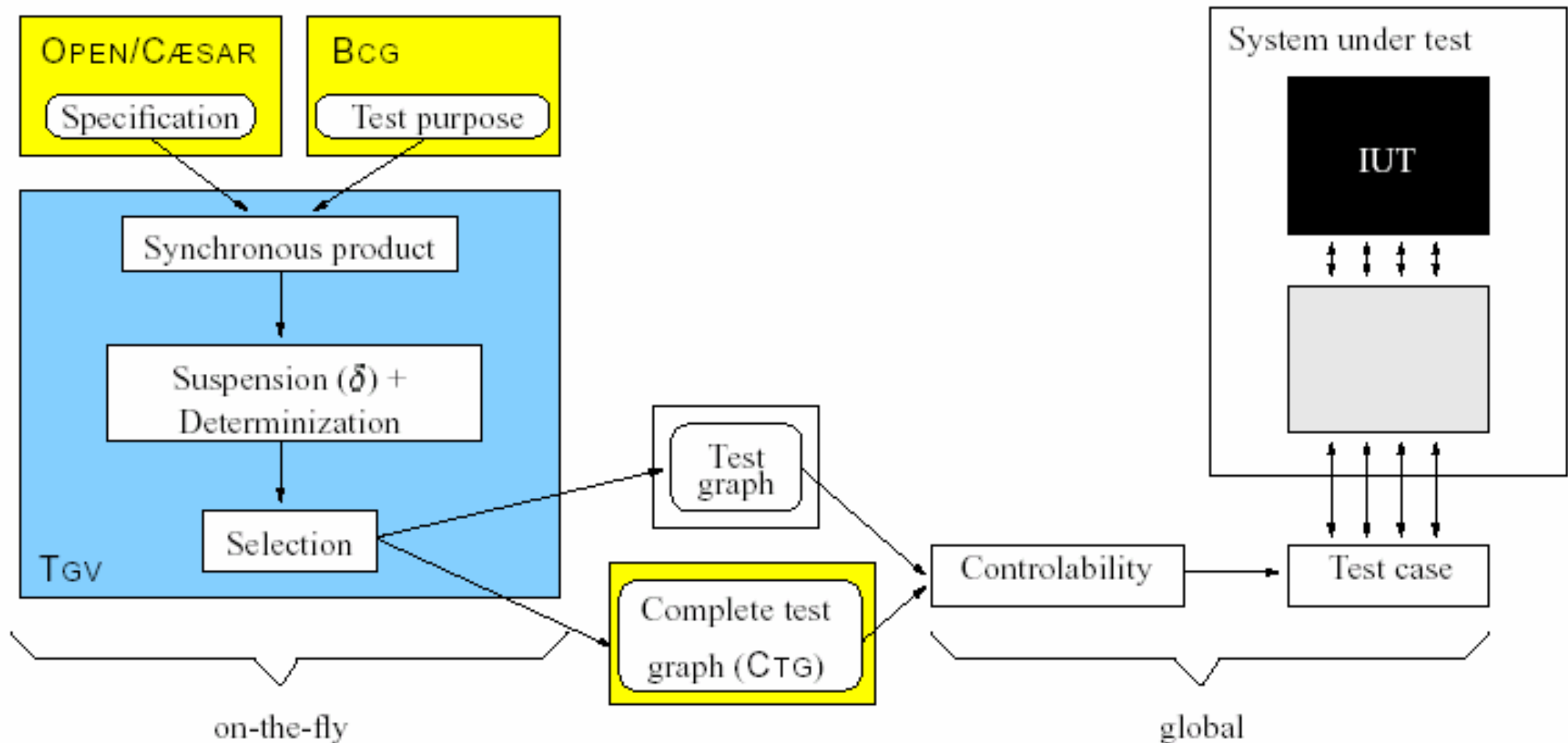


Local resolution with diagnostic



Conformance test generation using TGV

(Test Generation based on Verification technology)



[Fernandez-Jard-Jeron-Viho-96] [Jard-Jeron-05]

Translation into BES resolution with diagnostic

- *L2A (lead to accept)*: all states of the synchronous product $Spec \times TP$ from which an accepting state can be reached

$$\phi_{l2a} = \phi_{acc} \wedge \forall X. [-] (\phi_{acc} \Rightarrow X)$$

$$\phi_{acc} = \mu Y. acc \vee \langle - \rangle Y$$

- Translation to a BES:

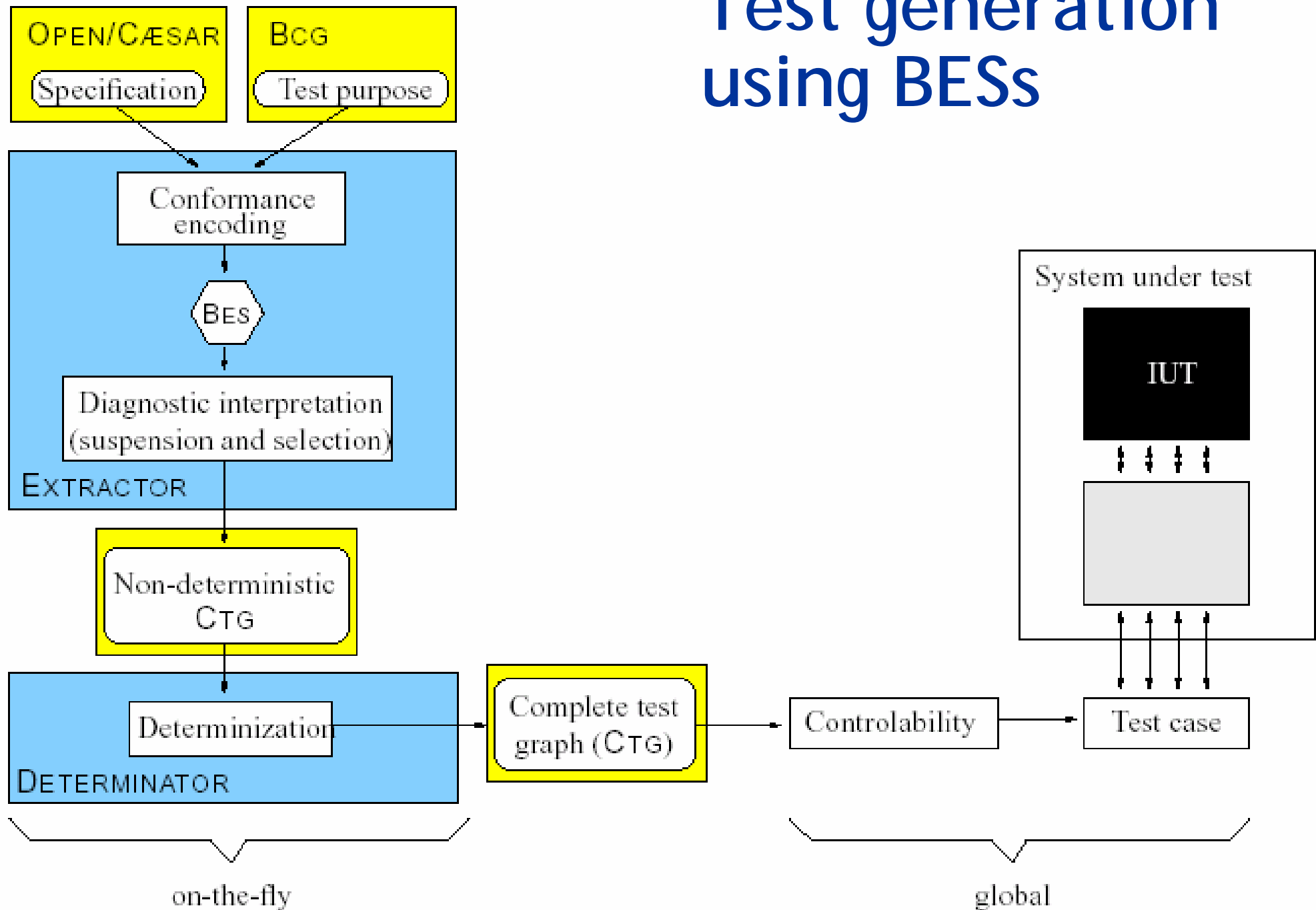
$$s \models \phi_{l2a} = Y_s \wedge X_s$$

$$\{ X_s =_{\forall} \bigwedge_{s \rightarrow s'} (Z_{s'} \vee X_{s'}) \} \quad \{ Y_s =_{\mu} acc_s \vee \bigvee_{s \rightarrow s'} Y_{s'} \}$$

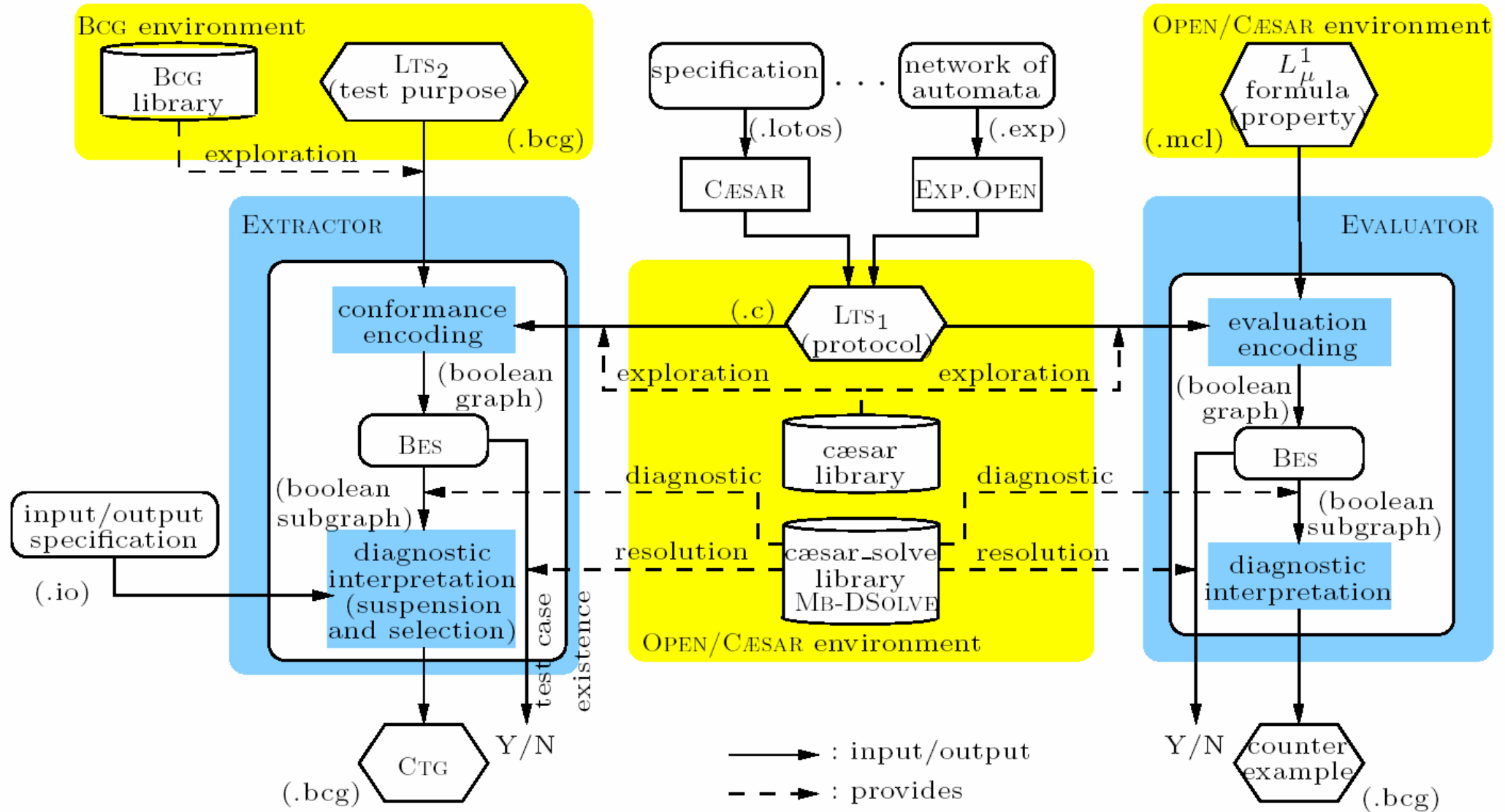
$$\{ Z_s =_{\forall} \neg acc_s \wedge \bigwedge_{s \rightarrow s'} Z_{s'} \}$$



Test generation using BESs



Tools architecture



Experiments

- **IDPOT** cluster
48 bi-Xeon
2.4 GHz, 1.5 Gb

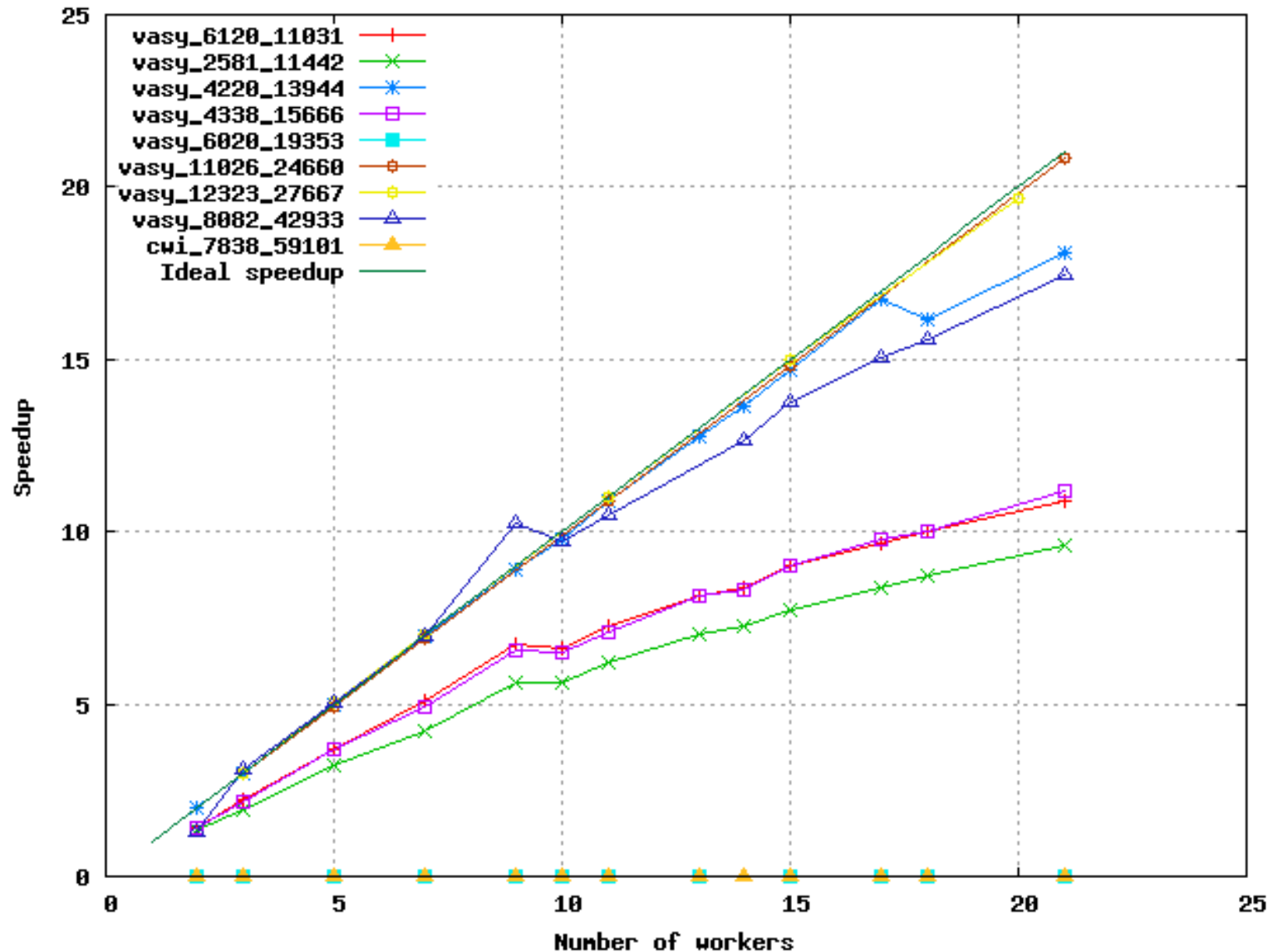


- **VLTS** benchmark suite

http://www.inrialpes.fr/vasy/cadp/resources/benchmark_bcg.html

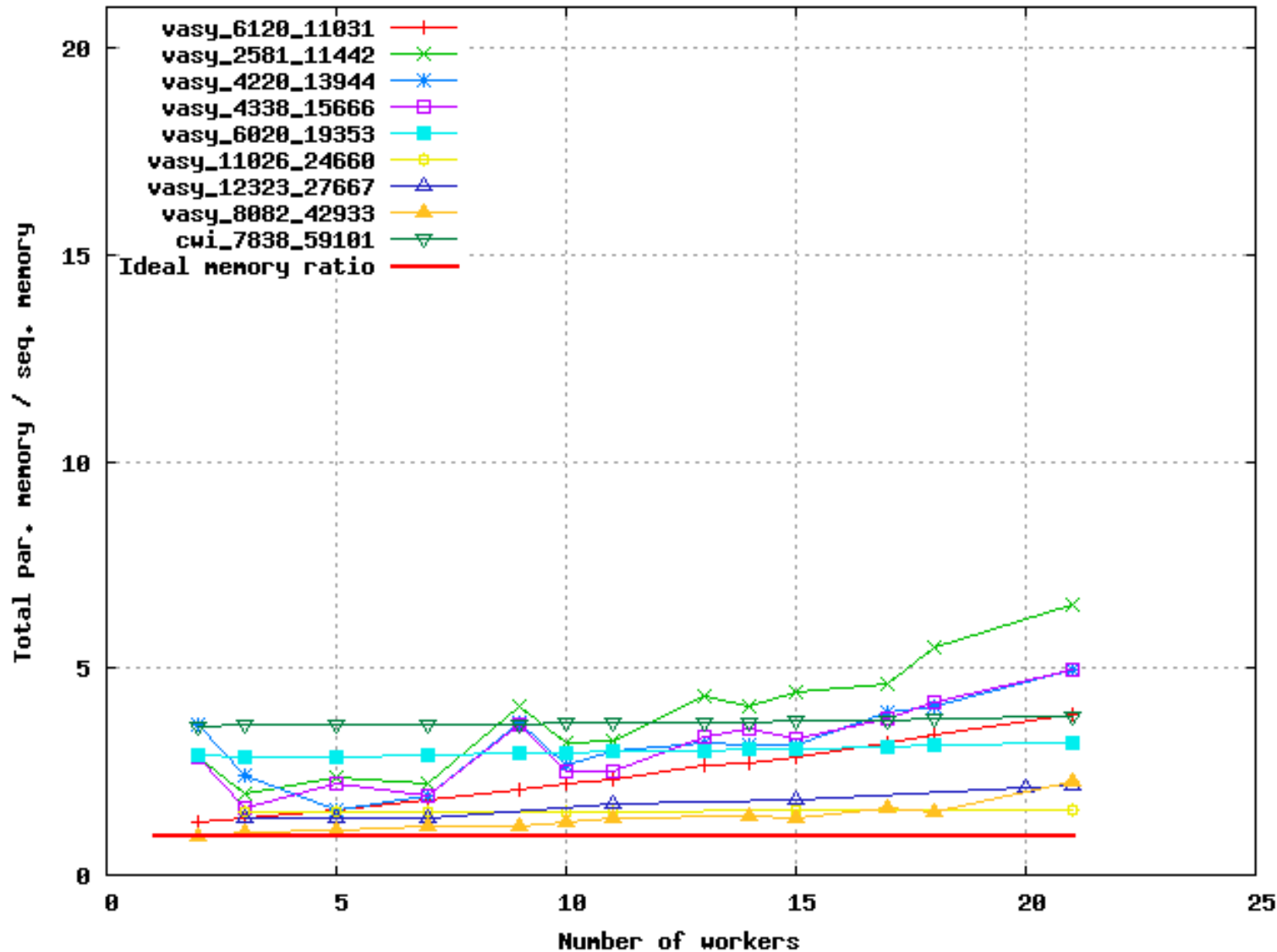
Distributed vs. sequential Evaluator

(speedup, absence of deadlock, VLTS)



Distributed vs. sequential Evaluator

(memory overhead, absence of deadlock, VLTS)



Distributed Evaluator vs. UppDMC

(absence of deadlock, VLTS)

EXAMPLE	absence of deadlock				
	truth	U (s)	U (MB)	E (s)	E (MB)
<i>vasy-2581-11442</i>	false	44	461	2	272
<i>vasy-4220-13944</i>	false	56	726	21	294
<i>vasy-4338-15666</i>	false	64	745	2	313
<i>vasy-6020-19353</i>	true	59	1 085	24	1 239
<i>vasy-6120-11031</i>	false	95	947	1	170
<i>cwi-7838-59101</i>	true	149	1 531	46	2 298
<i>vasy-8082-42933</i>	false	162	1 374	2	268

Evaluator: 21 Xeon / 2.4 GHz / 1.5 Gb

UppDMC: 25 bi-Pentium III / 500 MHz / 512 Mb



Distributed Evaluator vs. UppDMC

(presence of livelock, VLTS)

EXAMPLE	presence of livelock				
	truth	U (s)	U (MB)	E (s)	E (MB)
<i>vasy-2581-11442</i>	false	47	n.c.	7	844
<i>vasy-4220-13944</i>	false	67	n.c.	622	1 149
<i>vasy-4338-15666</i>	false	64	n.c.	11	1 203
<i>vasy-6020-19353</i>	true	125	n.c.	8	1 442
<i>vasy-6120-11031</i>	false	108	n.c.	13	1 092
<i>cwi-7838-59101</i>	true	314	n.c.	16	2 793
<i>vasy-8082-42933</i>	false	134	n.c.	24	2 401

Evaluator: 21 Xeon / 2.4 GHz / 1.5 Gb

UppDMC: 25 bi-Pentium III / 500 MHz / 512 Mb



Sequential Extractor vs. TGV

(generic TP - accepting state after 10 visible actions, VLTS)

EXAMPLE	TGV				(sequential) EXTRACTOR					
	time	MB	states	trans.	time	%	MB	%	states	trans.
<i>vasy-164-1619</i>	15'8s	242	100 319	231 266	3'47s	75	210	13	438 861	2 982 696
<i>vasy-166-651</i>	20'23s	242	170 657	586 602	1'41s	92	113	53	444 542	1 504 985
<i>cwi-371-641</i>	6'5s	1600	125 894	597 445	5'20s	12	310	81	1 912 260	3 163 177
<i>vasy-386-1171</i>	9s	11	3 319	3 892	7s	22	10	9	5 561	6 324
<i>vasy-1112-5290</i>	23s	33	10 827	20 888	13s	44	28	15	15 008	41 225
<i>b256</i>	597'4s	2322	264 194	854 786	139'22s	77	2772	-2	12 139 232	39 020 231

TGV:

- 1.82 times slower than Extractor + Determinator
- Produces CTGs between 30% and 50% smaller

“raw” CTGs
(contain τ -transitions)




Distributed Extractor + Determinator

(generic TP, 7 nodes, VLTS)

EXAMPLE	(distributed) EXTRACTOR		DETERMINATOR			
	time	MB	time	MB	states (final)	transitions (final)
<i>vasy-164-1619</i>	4'39s	470	4'40s	55	103 658	975 594
<i>vasy-166-651</i>	2'59s	335	2'27s	50	173 259	801 675
<i>cwi-371-641</i>	12'4s	880	25'8s	185	127 218	777 278
<i>vasy-386-1171</i>	16s	104	15s	6	2 452	3 894
<i>vasy-1112-5290</i>	27s	228	17s	7	8 369	41 225
<i>b256</i>	180'	6127	19'	459	527 875	1 709 058

final CTGs
 (without τ -transitions)
 strongly equivalent to
 those produced by TGV



Conclusion and future work

- **Summary**

- MB-DSolve: distributed local resolution of multi-block BESs
- Generic implementation using OPEN/CAESAR
- Two applications distributed & on-the-fly:
 - Model checking of alt-free mu-calculus (Evaluator 3.5)
 - Conformance test case generation (Extractor)
- Good speedups w.r.t. sequential versions
- Performance comparable with state-of-the-art tools (UppDMC, TGV)

- **Ongoing and future work**

- Further experiments and benchmarks
- Handling of heterogeneous architectures (grids)
- Other applications (discrete controller synthesis)

